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ros_control overview¶. The ros_control framework provides the capability to implement and manage robot controllers, that mainly consists of a feedback mechanism, most probably a PID loop,

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which can receive a setpoint, and control the output, typically effort, using the feedback from the actuators. The primary motivation of `ros_control` is the lack of realtime-safe communication layer in ROS.

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What is the first thing
that comes to mind
when you think of a

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robot? For many people it is a machine that imitates a human—like the androids in Star Wars, Terminator and Star Trek: The Next Generation. However much these robots capture our imagination, such robots still only inhabit Science Fiction.

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Introduction to
Robotics, H. Harry
Asada Department of
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Chapter 1 Introduction
Many definitions have
been suggested for
what we call a robot.
The word may conjure
up various levels of
technological
sophistication, ranging
from a simple material
handling device to a

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